



# **Smart transmitter/Gas Detector Head**

## **SD-1RI (TYPE HS)**

### **Safety Manual**

**Document Number : PT2E-218(Rev.17)**

[Note] SD-1RI(TYPE HS) is certificated by the functional safety (IEC 61508:2010 Part2 and Part3). To maintain the function described in the certificate, manage the detector head according to this manual.

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## Revision history

Rev	Details	Approved by	Reviewed by	Created by
0	Newly created	Masaru Ishibashi	Shinsuke Kogure	Ryouji Hayashi
		Feb 21, 2014	Feb 21, 2014	Feb 21, 2014
1	Erroneous description corrected	Masaru Ishibashi	Shinsuke Kogure	Ryouji Hayashi
		Apr 22, 2014	Apr 22, 2014	Apr 22, 2014
2	Erroneous description corrected	Masaru Ishibashi	Shinsuke Kogure	Ryouji Hayashi
		May 16, 2014	May 16, 2014	May 16, 2014
3	Corrected due to EXIDA audit findings	Masaru Ishibashi	Shinsuke Kogure	Ryouji Hayashi
		Jun 27, 2014	Jun 27, 2014	Jun 27, 2014
4	Erroneous description corrected	Masaru Ishibashi	Shinsuke Kogure	Ryouji Hayashi
		Jul 01, 2014	Jul 01, 2014	Jul 01, 2014
5	Corrected due to EXIDA audit findings	Masaru Ishibashi	Shinsuke Kogure	Ryouji Hayashi
		Sep 01, 2014	Sep 01, 2014	Sep 01, 2014
6	2-14 Update	Hiroki Muto	Noriaki Tsuchiya	Ryoji Hayashi
		Jan 17,2017	Jan 17,2017	Jan 17,2017
7	2-14 Update	Hiroki Muto	Noriaki Tsuchiya	Ryoji Hayashi
		Dec 5,2017	Dec 5,2017	Dec 5,2017
8	2-14 Update	Shinichi Yonemura	Masayuki Uchida	Yuki Saiki
		Apr 10,2018	Apr 10,2018	Apr 10,2018
9	2-14 Update	Hiroki Muto	Noriaki Tsuchiya	Ryoji Hayashi
		Oct 9,2019	Oct 9,2019	Oct 9,2019
10	2-14 Update	Hiroki Muto	Noriaki Tsuchiya	Ryoji Hayashi
		Dec 3,2019	Dec 3,2019	Dec 3,2019
11	2-14 Update	Hiroki Muto	Noriaki Tsuchiya	Ryoji Hayashi
		Mar 18,2020	Mar 18,2020	Mar 18,2020
12	2-14 Update	Hiroki Muto	Noriaki Tsuchiya	Ryoji Hayashi
		Jul 14,2020	Jul 14,2020	Jul 14,2020
13	2-14 Update	Hiroki Muto	Noriaki Tsuchiya	Saiki Yuuki
		Mar 15,2021	Mar 15,2021	Mar 15,2021
14	2-14 Update	Hiroki Muto	Noriaki Tsuchiya	Saiki Yuuki
		Jun 16,2021	Jun 16,2021	Jun 16,2021
15	2-9 Update	Hiroki Muto	Noriaki Tsuchiya	Yuuki Saiki
		Jul 02,2021	Jul 02,2021	Jul 02,2021
16	2-14 Update	Hiroki Muto	Noriaki Tsuchiya	Yuuki Saiki
		Jul 14,2021	Jul 14,2021	Jul 14,2021
17	2-9 and 2-14 Update	Shinsuke Kogure	Kazunori Yamada	Noriaki Tsuchiya
		Jul 18,2024	Jul 18,2024	Jul 18,2024

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# 1

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## **Purpose**

This safety manual describes the following information, for which users are responsible, when SD-1RI (TYPE HS) (hereinafter referred to as the detector head), a device certified by IEC 61508:2010 Part 2 SIL 2 capable and IEC 61508:2010 Part 3 SIL 3 capable, is used as part of the safety instrumented function: Proof test, repair and replacement, reliability data, product service life, environmental and usage restrictions, setting parameters, etc. To use the detector head safely, read this safety manual and all related documents.

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## 2

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# How to Use

## 2-1. Safety function

The safety function of the detector head includes the following:

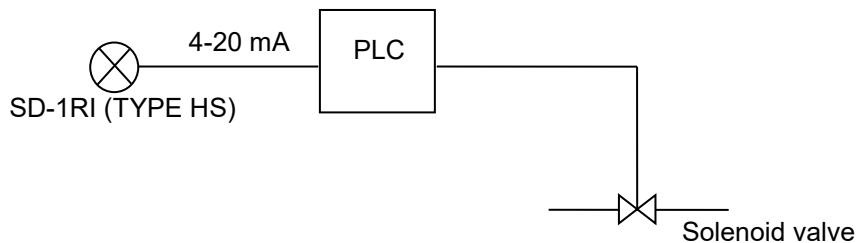
- Monitoring combustible gas concentration at sampling points.
- Outputting a current according to monitored gas concentration to the upper system side. The output function of the detector head is 4-20 mA output and HART communication output (\*).
- About 4-20 mA output

Measured combustible gas concentration and 4-20 mA output are in a proportional relationship. For example, 4 mA is output when concentration is 0%LEL, and 20 mA is output when concentration is 100%LEL. During a failure, a current of 3.6 mA or less or 21 mA or more is output.

\* HART communication output is not included in the safety function.

### System example

The following example shows a system where the solenoid valve is controlled and blocked through PLC.



## 2-2 Safety accuracy

Safety accuracy: 15%

- \* An internal part failure that causes a difference exceeding this accuracy is counted in the FMEDA failure rate.

## 2-3 Diagnosis response

Maximum response time for self-diagnosis results: 15 seconds

- \* It means that a part failure detected in self-diagnosis is notified within this time limit. This is a total time of a self-diagnosis test interval and a failure response time.

## 2-4 Setup

See the separate document "Operating Manual". Never fail to inspect parameters that are set.

## 2-5 Proof test

For a proof test interval, see the FMEDA report (No.RK 13/05-009 R001).

Proof test procedure

- (1) Never fail to bypass the safety function.
- (2) Confirm that the gas concentration reading on the detector head is zero.
- (3) Introduce a gas for calibration gas.
- (4) Check the gas response time and 4-20 mA output value.
- (5) Finish the procedure by resetting the bypass for the safety function.

\* A proof test must be run by a trained service man because performing it incorrectly may cause a malfunction of the detector head.

## 2-6 Repair and replacement

See the separate document "Operating Manual".

## 2-7 Startup time (initial clear time)

About the first 25 seconds after turning on the detector head is the initial clear time. During that period, a gas cannot be detected correctly.

## 2-8 Firmware update

To update firmware, the detector head must be returned to the RIKEN KEIKI factory.

## 2-9 Reliability data

Information such as the failure rate, failure mode, etc. is described in the FMEDA report (No.RK 13/05-009 R001 V3R3). See the separate document "FMEDA Report".  
To meet SIL2, use with HFT=0. To meet SIL3, use with HFT=1.

## 2-10 Product service life

Product service life: 10 years from the date of manufacture  
Reliability data in the FMEDA report are valid only during this period.

## 2-11 Required parameter settings

- During a burnout (failure), 4-20 mA output value becomes 3.6 mA or less or 21 mA or more.
- For security reasons, use the write protection function, which does not allow setting changes through HART communication.
- To use the detector head as the functional safety, never fail to follow the above item.

## 2-12 Environmental restrictions

For environmental restrictions, see the separate document "Operating Manual".

## 2-13 Application restrictions

For application restrictions, see the separate document "Operating Manual".

## 2-14 Configuration of the hardware / Software

The hardware and software versions that can be combined are as follows.

Hardware Version	Software Version
V1.0	V1.0
V1.0	V1.1
V1.1	V1.1
V1.1	V1.0
V1.1	V1.1-1
V1.0	V1.1-1
V1.2	V1.1
V1.2	V1.1-1

## 2-15. Definition of terms and abbreviations

### Terms

Safety	Freedom from unacceptable risk of harm
Functional Safety	The ability of a system to carry out the actions necessary to achieve or to maintain a defined safe state for the equipment / machinery / plant / apparatus under control of the system
Basic Safety	The equipment must be designed and manufactured such that it protects against risk of damage to persons by electrical shock and other hazards and against resulting fire and explosion. The protection must be effective under all conditions of the nominal operation and under single fault condition
Safety Assessment	The investigation to arrive at a judgment - based on evidence - of the safety achieved by safety-related systems
Fail-Safe State	State where solenoid valve is de-energized and spring is extended.
Fail Safe	Failure that causes the valve to go to the defined fail-safe state without a demand from the process.
Fail Dangerous	Failure that causes the valve to go to the defined fail-safe state without a demand from the process.
Fail Dangerous Undetected	Failure that is dangerous and that is not being diagnosed by automatic stroke testing.
Fail Dangerous Detected	Failure that is dangerous but is detected by automatic stroke testing.
Fail Annunciation Undetected	Failure that does not cause a false trip or prevent the safety function but does cause loss of an automatic diagnostic and is not detected by another diagnostic.
Fail Annunciation Detected	Failure that does not cause a false trip or prevent the safety function but does cause loss of an automatic diagnostic or false diagnostic indication.
Fail No Effect	Failure of a component that is part of the safety function but that has no effect on the safety function.
Low demand mode	Mode, where the frequency of demands for operation made on a safety-related system is no greater than twice the proof test frequency.



Abbreviations

FMEDA	Failure Modes, Effects and Diagnostic Analysis
HFT	Hardware Fault Tolerance
MOC	Management of Change. These are specific procedures often done when performing any work activities in compliance with government regulatory authorities.
PFDavg	Average Probability of Failure on Demand
SFF	Safe Failure Fraction, The fraction of the overall failure rate of a device that results in either a safe fault or a diagnosed unsafe fault.
SIF	Safety Instrumented Function, A set of equipment intended to reduce the risk due to a specific hazard (a safety loop).
SIL	Safety Integrity Level, Discrete level (one out of a possible four) for specifying the safety integrity requirements of the safety functions to be allocated to the E/E/PE safety-related systems where Safety Integrity Level 4 has the highest level of safety integrity and Safety Integrity Level 1 has the lowest.
SIS	Safety Instrumented System, Implementation of one or more Safety Instrumented Functions. A SIS is composed of any combination of sensor(s), logic solver(s), and final element(s).

End of the manual